Mindluster Platform

About the course Simulink Student Challenge

Reinforcement Learning Control for Wheeled Self-balancing Systems ... This project shows an interesting approach to developing a controller to a nonlinear system.

Technology Category's Courses

Course Lesson(8)

Lesson 1 : **Accelerated design development and flight testing of a UAV autopilot with Simulink**

Lesson 2 : **Development of arm controller for robotic satellite servicing**

Lesson 3 : **Modelling a ventilation system with Simulink**

Lesson 4 : **PID vitesse DC moteur via matlab simulink et MicrocontrÃ´leur PIC**

Lesson 5 : **Landing Gear Design simulation SIMULINK 2013**

Lesson 6 : **2013 Simulink Student Challenge IIT Kharagpur**

Lesson 7 : **Simulink challenge 2013 IPN**

Lesson 8 : **Simulink movie**

Related courses

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F5 BIG IP LTM

Cisco MPLS L essentiel

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